# STA TISTICAL PROPERTIES OP INHOMOGENEOUS SOLID MEDIA: CENTRAL MOMENT FUNCTIONS OF MATERIAL CHARACTERISTICS 

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Statistical properties of multicomponent inhomogeneous media are investigated. A general definition of the concentration and coordinate functional structure of central moment functions of material characteristics is presented. It is established that such functional structure is highly sensitive to differences in statistical properties of components. The class of symmetric media for which central moment functions are greatly simplified are considered.

1. The term material characteristics, as used here, comprises quantities of the type of tensors of the elasticity modulus, of permittivity and, also, scalars such as density, specific heat, etc. For simplicity of presentation tensor indices of material characteristics are almost everywhere omitted.

Let there be a random tensor field $\lambda(r)$ (for instance, of elasticity moduli). Extending the characteristic functions derived in $[1,2]$ for two-component media to the case of arbitrary number of components, we obtain

$$
f_{i}(\mathbf{r})= \begin{cases}1, \mathbf{r} \in U_{i}, & i \neq 1  \tag{1.1}\\ 0, \mathbf{r} \notin U_{i}, & \sum_{i=1}^{N} U_{i}=U\end{cases}
$$

where $U_{i}$ is the region occupied by the $i$-th component and $N$ is the number of components. The characteristic function $f_{1}$ for the first component is determined by the obvious equality

$$
\begin{equation*}
\sum_{i=1}^{N} f_{i}(r)=1 \tag{1.2}
\end{equation*}
$$

The separation of the first component is not due here to any specific reason. We shall, however, always have in view the matrix medium in which a particular part is played by at least one component-matrix, as the simplest example of such medium.

Using (1.1) we define the random field $\lambda(\mathbf{r})$ by the formula

$$
\begin{equation*}
\lambda(\mathbf{r})=\lambda_{1}+\sum_{i=2}^{N} \Delta \lambda_{i} f_{i}(\mathbf{r}) \equiv \lambda_{1}+\Delta \lambda_{i} f_{i}(\mathbf{r}), \quad \Delta \lambda_{i} \equiv \lambda_{i}-\lambda_{1} \tag{1.3}
\end{equation*}
$$

where $\lambda_{i}$ is the value of $\lambda$ for the $i$-th component.
The fluctuation $\lambda^{\prime \prime}$ of field $\lambda$ is

$$
\begin{equation*}
\lambda^{\prime \prime}(\mathbf{r})=\Delta \lambda_{i} f_{i}^{\prime \prime}(\mathbf{r}), \quad x^{\prime \prime}(\mathbf{r}) \equiv x(\mathbf{r})-\langle x(\mathbf{r})\rangle \tag{1.4}
\end{equation*}
$$

where angle brackets denote statistical averaging.
The random field $\lambda$ (r) may be specified either by moment or central moment functions of various orders. The moment function of order $\omega$ of field $\lambda$ is by definition of the form $[3,4]$

$$
\begin{equation*}
M_{\omega}\left(\mathbf{R}_{n}\right)=\left\langle\left[\lambda\left(\mathbf{r}_{1}\right) \otimes\right]^{\omega_{1}} \cdots\left[\lambda\left(\mathbf{r}_{n}\right) \otimes\right]^{\omega_{n}}\right\rangle, \quad \mathbf{R}_{n} \equiv\left(\mathbf{r}_{1}, \mathbf{r}_{2}, \ldots, \mathbf{r}_{n}\right) \tag{1,5}
\end{equation*}
$$

For the central moment function of order $\omega$ we correspondingly have

$$
\begin{equation*}
\mu_{\omega}\left(\mathbf{R}_{n}\right)=\left\langle\left[\lambda^{\prime \prime}\left(\mathbf{r}_{1}\right) \otimes\right]^{\omega_{1}} \cdots\left[\lambda^{\prime \prime}\left(\mathbf{r}_{n}\right) \otimes\right]^{\omega_{n}}\right\rangle, \quad \omega=\sum_{a=1}^{n} \omega_{\alpha} \tag{1.6}
\end{equation*}
$$

In (1.5) and (1.6) the symbol $\otimes$ denotes a direct tensor product.
It is readily seen [5] that the use of characteristic functions $f_{i}$ makes it possible to reduce the calculation of $M_{\omega}$ to the determination of function

$$
P_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=\left\langle f_{i}\left(\mathbf{r}_{1}{ }^{i}\right) f_{j}\left(\mathbf{r}_{2}{ }^{j}\right) \ldots f_{k}\left(\mathbf{r}_{n}{ }^{k}\right)\right\rangle, \mathbf{R}_{n}^{i j \ldots k} \equiv\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}, \ldots, \mathbf{r}_{n}{ }^{k}\right)\left(\mathbf{1 .}^{i}{ }^{i}\right)
$$

which has the meaning of probability that points $\mathbf{r}_{1}{ }^{\boldsymbol{i}}, \mathbf{r}_{2}^{j}, \ldots, \mathbf{r}_{n}{ }^{k}$ belong, respectively, to regions $U_{i}, U_{j}, \ldots, U_{k}$, where $i, j, \ldots, k \neq 1$. The additional superscript at the radius vector indicates the region to which the respective point belongs. The introduced function was similarly investigated in [2] in the case of two-component medium.

The probability $P_{i j \ldots k}^{n}$ is invariant with respect to the simultaneous permutation of coordinates of points and of indices. Furthermore they have the following properties:

$$
\begin{align*}
& \sum_{i=1}^{N} P_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=P_{j \ldots k}^{n-1}\left(\mathbf{R}_{n-1}^{j \ldots k}\right)  \tag{1.8}\\
& P_{i j \ldots l}^{n} \ldots \ldots l \\
& \left(\mathbf{R}_{q}^{i j \ldots l}, \mathbf{r}, \ldots, \mathbf{r}\right)=P_{i j \ldots l}^{q}\left(\mathbf{R}_{q}^{i j \ldots l}\right), \quad \mathbf{r} \equiv \mathbf{r}_{q}{ }^{l} \\
& P_{i j \ldots l m \ldots k .}^{n}\left(\mathbf{R}_{q}^{i j \ldots l} \mid \overline{\mathbf{R}}_{n \ldots q}^{m \ldots k}\right)=P_{i j \ldots l}^{q}\left(\mathbf{R}_{q}^{i j \ldots l}\right) P_{m \ldots k}^{n-q}\left(\overline{\mathbf{R}}_{n-q}^{m \ldots k}\right) \\
& \overline{\mathbf{R}}_{n \ldots q}^{m \ldots \ldots} \equiv\left(\mathbf{r}_{q+1}^{m}, \ldots, \mathbf{r}_{n}{ }^{k}\right)
\end{align*}
$$

where the vertical stroke separates the groups of points $\mathbf{R}_{q}{ }_{q} \ldots . . l$ and $\overline{\mathbf{R}}_{n-q}^{m \ldots k}$ which are at infinitely great distances from each other; the total number of indices $i j$. . . $l$ is $q$, and the number of indices $l \ldots l$ and $m \ldots k$, and also the number of variables $\mathbf{r}, \ldots, \mathbf{r}$ is $(n-q)$.

Below we assume that the field $f_{i}(\mathbf{r})$ is statistically homogeneous and isotropic, because of which functions $P_{i j \ldots k}^{n}$ are invariant with respect to translations and rotations. Hence

$$
\begin{equation*}
P_{i}^{1}\left(\mathbf{r}_{1}^{i}\right)=v_{i}, \quad v_{i}=V_{i} / V, \quad V=\sum_{i=1}^{N} V_{i} \tag{1.9}
\end{equation*}
$$

where $v_{i}$ is the volume concentration of the $i$-th component.
Using (1.8) we similarly represent $P_{i j}{ }^{2}$ in the form

$$
\begin{equation*}
P_{i j}{ }^{2}\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}\right)=v_{i} \delta_{i j} \varphi_{0}{ }^{2}\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}\right)+v_{i} v_{j} \varphi_{1}{ }^{2}\left(\mathbf{r}_{1}{ }^{1}, \mathbf{r}_{2}{ }^{j}\right), \quad i, i \neq 1 \tag{1.10}
\end{equation*}
$$

where, as in (1.8) summation is not carried out with respect to the twice occuring in dices, and functions $\varphi_{q}{ }^{2}$ satisfy conditions

$$
\begin{equation*}
\varphi_{0}^{2}\left(\mathbf{r}_{1}^{i}, \mathbf{r}_{1}^{i}\right)=\varphi_{1}^{2}\left(\mathbf{r}_{1}{ }^{i} \mid \mathbf{r}_{2}^{j}\right)=1, \quad \varphi_{0}^{2}\left(\mathbf{r}_{1}^{i} \mid \mathbf{r}_{2}^{j}\right)=\varphi_{1}^{2}\left(\mathbf{r}_{1}^{i}, \mathbf{r}_{1}^{i}\right)=0 \tag{1.11}
\end{equation*}
$$

If certain constraints are imposed on field $f_{i}(\mathbf{r})$, functions $\varphi_{q}{ }^{2}$ can be obtained in explicit form [5].

Extending (1.10) to the case of arbitrary $n$ in the notation of (1.8) we have

$$
\begin{align*}
& P_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n-1} v_{i j \ldots k}^{q} \Psi_{q}^{n}\left(\mathbf{R}_{q}^{i j \ldots l} ; \overline{\mathbf{R}}_{n \ldots q}^{m \ldots k}\right)  \tag{1.12}\\
& P^{\circ}=1, \quad i, j \ldots, k \neq 1 \\
& v_{i j \ldots k}^{q}=v_{i} v_{j} \ldots v_{l} \sum_{p=2}^{N} v_{p} \delta_{m p} \ldots \delta_{k p}, \quad \mathbf{R}_{n}^{i j \ldots k}=\left(R_{q}^{i j \ldots l}, \overline{\mathbf{R}}_{n-q}^{m \ldots k}\right)
\end{align*}
$$

where functions $\varphi_{q}{ }^{n}$ have $q$ separated points, and summation is carried out over all nonidentical permutations of $\sigma_{n}$, i. e. of the first $n$ (in this case of all) points with simultaneous permutation of respective indices. The asymptotic formulas for these follow form (1.8) and are of a form similar to (1.11).

Note that function $\varphi_{n-1}^{n}$ does not contain the separated point.
In the opposite case, taking into account the total symmetry of $v_{i j \ldots k}^{n}=v_{i} v_{j}$ $\cdots v_{h}$, they are symmetrized owing to the action of $\sigma_{n}$.
As an example, we adduce the formula for the three-point probability

$$
\begin{align*}
& P_{i j k}^{3}\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}, \mathbf{r}^{k}\right)=\varphi_{0}{ }^{3}\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}, \mathbf{r}_{3}{ }^{k}\right) \sum_{p=2}^{N} v_{p} \delta_{i p} \delta_{j p} \delta_{k p}+  \tag{1.13}\\
& \varphi_{1}{ }^{3}\left(\mathbf{r}_{1}{ }^{i} ; \mathbf{r}_{2}{ }^{j}, \mathbf{r}_{3}{ }^{k}\right) v_{i} \sum_{p=2}^{N} v_{p} \delta_{j p} \delta_{k p}+ \\
& \varphi_{1}{ }^{3}\left(\mathbf{r}_{2}{ }^{j} ; \mathbf{r}_{3}^{k}, \mathbf{r}_{1}{ }^{i}\right) v_{j} \sum_{p=2}^{N} v_{p} \delta_{i p} \delta_{p p}+ \\
& \varphi_{1}{ }^{3}\left(\mathbf{r}_{3}{ }^{k} ; \mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}\right) v_{k} \sum_{p=2}^{N} v_{p} \delta_{i p} \delta_{j p}+v_{i} v_{j} v_{k} \varphi_{2}{ }^{3}\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}, \mathbf{r}_{3}{ }^{k}\right)
\end{align*}
$$

Functions $\varphi_{q}{ }^{n}$ introduced in (1.12) can be associated with various probabilities. Thus, for instance, the probability that point $\mathbf{r}_{1}{ }^{i}$ belongs to region $U_{2}$, while points $\mathbf{r}_{2}{ }^{\prime}$ and $\mathbf{r}_{3}{ }^{k}$ belong to region $U_{3}$, according to (1.13), is

$$
\begin{equation*}
P_{233}^{3}\left(\mathbf{R}_{3}\right)=v_{2} v_{\mathbf{3}} \varphi_{1}{ }^{3}\left(\mathbf{r}_{1} ; \mathbf{r}_{2}, \mathbf{r}_{3}\right)+v_{2} v_{3} v_{3} \varphi_{2}{ }^{3}\left(\mathbf{R}_{3}\right) \tag{1.14}
\end{equation*}
$$

and simultaneously function $\varphi_{2}{ }^{3}$ determines the probability that all three points belong to different regions

$$
\begin{equation*}
P_{234}^{3}\left(\mathbf{R}_{3}\right)=v_{2} v_{3} v_{4} \varphi_{2}{ }^{3}\left(\mathbf{R}_{3}\right) \tag{1.15}
\end{equation*}
$$

In addition to probability $P_{i j \ldots k}^{n}$, which has the meaning of the $n$-th order moment of field $f_{i}$, it is expedient to introduce in the analysis its central moment

$$
\begin{equation*}
T_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=\left\langle f_{i}^{\prime \prime}\left(r_{1}^{i}\right) f_{j}^{\prime \prime}\left(\mathbf{r}_{2}^{j}\right) \ldots f_{k}^{\prime \prime}\left(\mathbf{r}_{u}{ }^{k}\right)\right\rangle \tag{1.16}
\end{equation*}
$$

related to $P_{i j \ldots k}^{n}$ by the formula

$$
\begin{equation*}
T_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n}(-1)^{q} v_{i} v_{j} \ldots v_{l} P_{m \ldots k}^{n-q}\left(\overline{\mathbf{R}}_{n-q}^{m \ldots k}\right) \tag{1.1,~}
\end{equation*}
$$

The summation in (1.17) over permutations of $n$ points results in the appearance of $N_{k}=n!/[k!(n-k)!]$ terms of the form $v_{i} v_{j} \ldots v_{l} P_{m \ldots k}^{n-q}$ whose dependence on coordinates is determined by the respective set of ( $n-q$ ) points from the full set of $n$ points.

The calculation of central moments $\mu_{\omega}$ reduces to the determination of functions $T_{1 j \ldots k}^{n}$.
2. We transform functions $P_{i \sum_{2} \ldots k}^{n}$ and $T_{i j \ldots k}^{n}$ so as to obtain their explicit expressions in terms of dispersion $D_{i j \ldots k}^{n_{j}}$ of the characteristic function $f_{i}$. By dispersion $D_{i j \ldots k}^{n}$ we understand the value of functions $T_{i j \ldots k}^{n}$ when $\mathbf{r}_{1}{ }^{i}=\mathbf{r}_{2}{ }^{3}=\ldots=\mathbf{r}_{n}{ }^{k}$, i. e. when $\mathbf{R}_{n}^{i j \ldots k}=0$.

Taking into account that according to (1.7) or (1.12)

$$
\begin{equation*}
P_{i j \ldots k}^{n}(0)=\sum_{p=2}^{N} v_{p} \delta_{i p} \delta_{j p} \ldots \delta_{k p} \tag{2.1}
\end{equation*}
$$

from (1.17) with allowance for definition (1.12) we obtain

$$
\begin{equation*}
D_{i j \ldots k}^{n} \equiv T_{i j \ldots k}^{n}(0)=\sum_{\mathbf{o}_{n}} \sum_{q=0}^{n}(-1)^{q} v_{i j \ldots k}^{q} \tag{2.2}
\end{equation*}
$$

In what follows we shall need functions

$$
\begin{align*}
& \pi_{q}^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right)=\sum_{\sigma_{q}} \sum_{t=0}^{q} \varphi_{t}{ }^{n}\left(\mathbf{R}_{t} ; \overline{\mathbf{R}}_{n-t}\right)  \tag{2.3}\\
& \pi_{0}^{\circ}=\pi_{1}^{1}=1, \quad \pi_{n-\mathbf{1}}^{n}=0 \\
& \tau_{q}{ }^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right)=\sum_{\sigma_{q}} \sum_{t=0}^{q}(-1)^{t} \pi_{t}^{n-q+t}\left(\mathbf{r}_{q-t+1}, \ldots, \mathbf{r}_{q} ; \overline{\mathbf{R}}_{n-q}\right) \\
& \tau_{0}^{\circ}=\tau_{1}{ }^{1}=\tau_{n-1}^{n}=0
\end{align*}
$$

where in order to avoid clumsiness of formulas superscripts at radius vectors are omitted. Functions (2.3) satisfy certain limit conditions implied by (1.8) in the meaning of (1.11).

From this, for instance for $n=2$, we have

$$
\begin{align*}
& \pi_{0}{ }^{2}\left(\mathbf{R}_{2}\right)=\tau_{0}{ }^{2}\left(\mathbf{R}_{2}\right)=\varphi_{0}{ }^{2}\left(\mathbf{R}_{2}\right), \quad \pi_{2}{ }^{2}\left(\mathbf{R}_{2}\right)=\varphi_{0}{ }^{2}\left(\mathbf{R}_{2}\right)+\varphi_{1}{ }^{2}\left(\mathbf{R}_{2}\right)  \tag{2.4}\\
& \tau_{2}{ }^{2}\left(\mathbf{R}_{2}\right)=\pi_{0}{ }^{\circ}-\pi_{1}{ }^{1}\left(\mathbf{r}_{1}\right)-\pi_{1}{ }^{1}\left(\mathbf{r}_{2}\right)+\pi_{2}{ }^{2}\left(\mathbf{R}_{2}\right)=\pi_{2}{ }^{2}\left(\mathbf{R}_{2}\right)-1
\end{align*}
$$

Using (2.3) functions (1.12) and (1.17) can be reduced to the form

$$
\begin{align*}
& P_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n} v_{i} v_{j} \ldots v_{l} D_{m \ldots k}^{n-q} \pi_{q}^{n}\left(\mathbf{R}_{q}^{i j \ldots l} ; \bar{R}_{n \ldots q}^{m \ldots k}\right)  \tag{2.5}\\
& T_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n}(-1)^{q} v_{i} v_{j} \ldots v_{l} D_{m \ldots k}^{n-q} \tau_{q}^{n}\left(\mathbf{R}_{q}^{i j \ldots l} ; \overline{\mathbf{R}}_{n-\mu}^{m \ldots k}\right)
\end{align*}
$$

The advantage of formula (2.5) over (1.12) and (1.17) is in that in it dispersions of the characteristic function appear in explicit form, which is particularly convenient for the calculation of $\mu_{\omega}$. Below we consider central moments $\mu_{\omega}$ in the case when all $\omega_{a}=1$.

Using the definitions (1.4), (1.6), and (1.16) we obtain

$$
\begin{equation*}
\mu_{1 \mathbf{1} \ldots 1}\left(\mathbf{R}_{n}\right) \equiv \mu_{n}\left(\mathbf{R}_{n}\right)=T_{i j \ldots k}^{n}\left(\mathbf{R}_{n}^{i j \ldots k}\right) \Delta \lambda_{i} \otimes \Delta \lambda_{j} \otimes \ldots \otimes \Delta \lambda_{k} \tag{2.6}
\end{equation*}
$$

where summation with respect to indices $i, j, \ldots, k$, which denote the component ordinal numbers, is assumed to be from two to $N$. The substitution into this formula of the expression $T_{i j \ldots k}^{n}$ in (2.5) yields

$$
\begin{align*}
& \mu_{n}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n}(-1)^{q} v_{i} v_{j} \ldots v_{l} \times  \tag{2,1}\\
& \quad D_{m \ldots k}^{n-q} \Delta \lambda_{i} \otimes \Delta \lambda_{j} \otimes \ldots \otimes \Delta \lambda_{k} \tau_{q}^{n}\left(\mathbf{R}_{q}^{i j \ldots l} ; \overline{\mathbf{R}}_{n \ldots q}^{m \ldots k}\right)
\end{align*}
$$

We use (2.7) for defining the second order central moment of the tensor field $\lambda_{\alpha}$, where $\alpha$ is to be understood to represent the totality of tensor indices of field $\lambda$. From (2.7) we have

$$
\begin{equation*}
\mu_{\alpha \beta}\left(\mathbf{R}_{2}\right)=\left[v_{i} v_{j} \tau_{2}{ }^{2}\left(\mathbf{R}_{2}^{i j}\right)+D_{i}{ }^{2} \tau_{0}{ }^{2}\left(\mathbf{R}_{2}{ }^{i j}\right)\right] \Delta \Delta_{i i \alpha} \lambda_{i} \Delta \lambda_{j \beta} \tag{2.8}
\end{equation*}
$$

Because summation in formulas (2.7) and (2.8) is carried out with respect to coordinates, the dependence of central moments of field $\lambda$ on coordinates and tensors is not separated. It should also be noted that functions $\tau_{q}{ }^{n}$, as well as functions $\varphi_{q}{ }^{n}$, depend not only on coordinates of points which determine the dependence of $\mu_{n}$ on coordinates but, also, on that to which components belong the points contained in $\tau_{q}{ }^{n}$. Thus in the general case $\tau_{2}{ }^{2}\left(\mathbf{r}_{1}{ }^{i}, \mathbf{r}_{2}{ }^{j}\right) \neq \mathbf{r}_{2}{ }^{2}\left(\mathbf{r}_{1}{ }^{j}, \mathbf{r}_{2}{ }^{i}\right)$, when $i \neq j$.

The dependence of $\tau_{q}{ }^{n}$ on component indices may be due to their differences related to the spatial distribution and to the shape of regions occupied by components. Furthermore it may be due to incomplete definition of the dependence on concentration by coefficients $v_{i} v_{j} \ldots v_{i} D_{m \ldots k}^{n-q}$ in (2.5).

Let the considered medium be such that function $\tau_{q}{ }^{n}$ is symmetric with respect to permutations of indices of components when the position of points $\mathbf{r}_{1}, \mathbf{r}_{2}, \ldots, \mathbf{r}_{n}$ is fixed. Functions ${\tau_{q}}^{n}$ then satisfy the condition

$$
\begin{equation*}
\boldsymbol{\tau}_{q}{ }^{n}\left(\mathbf{R}_{q}^{i j \ldots l} ; \overline{\mathbf{R}}_{n-q}^{m \ldots k}\right)=\boldsymbol{\tau}_{q}{ }^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right) \tag{2.9}
\end{equation*}
$$

which we shall call the condition of symmetry. It results in that the differences in statistical properties of all components, except the first, reduce in conformity with (2.5) to their concentration. A similar condition can also be formulated for functions $\pi_{q}{ }^{n}$.

Condition (2.9) considerably simplifies the expression for the central moment $\mu_{n}$. The substitution of (2.9) into ( 2.7 ) yields

$$
\begin{align*}
& \mu_{n}^{(1)}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n}\left[\lambda_{1}^{\prime \prime} \otimes\right]^{q} D_{n-q}^{(\lambda)} \tau_{q}^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right)  \tag{2.10}\\
& \left(\hat{\lambda}_{1}^{\prime \prime}=-v_{i} \Delta \lambda_{i}, D_{n}^{(\lambda)} \equiv \mu_{n}(0)\right)
\end{align*}
$$

where the first of equalities appearing in parentheses follows from (1.4). The superscript at $\mu_{n}$ is shown here for stressing the importance of the first component. A medium that satisfies conditions (2.9) and (2.10) is called below almost symmetric.

The described above determination of function $\mu_{n}$, obtained with the use of characteristic function (1.1), may also be effected by using functions of the form

$$
f_{i}^{(p)}(\mathbf{r})= \begin{cases}1, \mathbf{r} \in U_{i}, & i \neq p  \tag{2.11}\\ 0, \mathbf{r} \notin U_{i}, & \sum_{i=1}^{N} U_{i}=U\end{cases}
$$

Function (2.11) defines the same medium as function (1.1), hence the result of calculating $\mu_{n}$ must evidently be the same. However in order to represent $\mu_{n}$ in the form (2.7) it is necessary to bear in mind that functions $\tau_{q}{ }^{n}$ are, generally speaking, different, $\Delta \lambda_{i}=\lambda_{i}-\lambda_{p}$, and summation with respect to subscripts $i, j, \ldots, k$ excludes the $p$-th component.

In the case of almost symmetric medium the calculation of $\mu_{n}$ by (1.1) yields (2.10), while the use of (2.11) leads to an expression of the form (2.7). Hence when the medium contains a component whose statistical properties differ from the remaining it is important to properly select the characteristic function. This must be done so that the separated component would have that singularity.

Let now the medium be such that condition (2.9) is satisfied for functions $\tau_{q}{ }^{n}$ determined by (1.1), as well as by (2.11). Then instead of (2.9) we have

$$
\begin{equation*}
\mu_{n}^{(i)}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n}\left[\lambda_{i}^{\prime \prime} \otimes\right]^{q} D_{n-q}^{(\lambda)} \tau_{q}^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right), \quad i=1 \div N \tag{2.12}
\end{equation*}
$$

A medium for which the central moment can be represented in the form (2.12) is called symmetric. For such medium the use of the superscript is devoid of any meaning.

Taking into account that any of $\mu_{n}^{(i)}$ can be taken as $\mu_{n}$, we write

$$
\mu_{n}\left(\mathbf{R}_{n}\right)=\sum_{i=1}^{N} v_{i} \mu_{n}^{(i)}\left(\mathbf{R}_{n}\right)=\left\langle\mu_{n}\left(\mathbf{R}_{n}\right)\right\rangle
$$

The substitution into that formula of (2.12) yields

$$
\begin{align*}
& \mu_{n}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n} D_{q}^{(\lambda)} D_{n-q}^{(\lambda)} \tau_{q}^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right)  \tag{2.13}\\
& D_{q}^{(\lambda)} \equiv \sum_{i=1}^{N} v_{i}\left[\lambda_{i}^{\prime \prime} \otimes\right]^{q}
\end{align*}
$$

Functions $T_{i j \ldots k}^{\mathfrak{n}}$, that correspond to (2.13) are of the form

$$
\begin{equation*}
T_{i j \ldots k}^{n}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n} D_{i j \ldots l}^{q} D_{m \ldots k}^{n-q} \tau_{q}{ }^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right), \tau_{2}{ }^{2}=0 \tag{2.14}
\end{equation*}
$$

It can be shown that $\tau_{2}{ }^{2}$ is zero by using the condition implied by (2.13) similar to ( 2,9 ) imposed on $\tau_{q}{ }^{n}$.

For $n=2,3,4$ for the tensor field $\lambda_{\alpha}$ from (2.13) we have

$$
\begin{aligned}
& \mu_{\alpha \beta}\left(\mathbf{R}_{2}\right)=D_{\alpha \beta}^{(\lambda)} \tau_{0}{ }^{2}\left(\mathbf{R}_{2}\right), \mu_{\alpha \beta \gamma}\left(\mathbf{R}_{3}\right)=D_{\alpha \beta \gamma}^{(\lambda)} \tau_{0 s}^{3}\left(\mathbf{R}_{\mathbf{s}}\right) \\
& \tau_{0 s}{ }^{n} \equiv \tau_{0}{ }^{n}+\tau_{n}{ }^{n} \\
& \mu_{\alpha \beta \gamma \sigma}\left(\mathbf{R}_{4}\right)-D_{\alpha \beta \gamma \delta}^{(\lambda)} \tau_{0 s}{ }^{4}\left(\mathbf{R}_{4}\right)+D_{\alpha \beta}^{(\lambda)} D_{\gamma \delta}^{(\lambda)} \tau_{2 s}{ }^{4}\left(\mathbf{r}_{1}, \mathbf{r}_{2} ; \mathbf{r}_{3}, \mathbf{r}_{4}\right)+ \\
& \quad D_{\alpha \gamma}^{(\lambda)} D_{\beta 0}^{(\lambda)} \tau_{2 s}{ }^{4}\left(\mathbf{r}_{1}, \mathbf{r}_{3} ; \mathbf{r}_{2}, \mathbf{r}_{4}\right)+D_{\alpha \delta}^{(\lambda)} D_{\beta \gamma}^{(\lambda)} \tau_{2 s}\left(\mathbf{r}_{1}, \mathbf{r}_{4} ; \mathbf{r}_{2}, \mathbf{r}_{3}\right) \\
& \tau_{2 s}{ }^{4}\left(\mathbf{r}_{i}, \mathbf{r}_{j} ; \mathbf{r}_{k}, \mathbf{r}_{l}\right) \equiv \mathbf{\tau}_{2}{ }^{4}\left(\mathbf{r}_{i}, \mathbf{r}_{j} ; \mathbf{r}_{k}, \mathbf{r}_{l}\right)+\tau_{2}{ }^{4}\left(\mathbf{r}_{k}, \mathbf{r}_{l} ; \mathbf{r}_{i}, \mathbf{r}_{j}\right)
\end{aligned}
$$

The explicit form of functions $\tau_{0_{s}}{ }^{n}$ was obtained in [5] in the course of analysis of a random tensor field of the Markovian type. In summarizing the obtained results it is necessary to stress that the invariance (either partial or total) of the medium with respect to inversion (of all or a part) of components leading to (2.13) or (2.12) considerably simplifies the form of central moments and their dependence on concentration and coordinates. (Inversion of components $i$ and $j$ is denoted by $i \leftrightarrow j$ and implies, first, their transposition in space and, second, the substitution $v_{i} \leftrightarrow v_{j}$.)
3. Let us consider the case of the two-component medium. Formulas obtained in Sects. 1 and 2 are simplified, since everywhere, where the first component is taken as the separated one, it is necessary to use the substitution $i=j=\cdots=k=2$, which makes it possible to completely discard these subscripts.

Thus, for instance, from (1.7) we have

$$
\begin{align*}
& P_{22 \ldots 2}^{n}\left(\mathbf{R}_{n}^{22 \ldots 2}\right)=\left\langle f_{2}\left(\mathbf{r}_{1}{ }^{2}\right) f_{2}\left(\mathbf{r}_{2}{ }^{2}\right) \ldots f_{2}\left(\mathbf{r}_{n}{ }^{2}\right)\right\rangle=  \tag{3.1}\\
& \left\langle f\left(\mathbf{r}_{1}\right) f\left(\mathbf{r}_{2}\right) \ldots f\left(\mathbf{r}_{n}\right)\right\rangle \equiv P_{n}\left(\mathbf{R}_{n}\right)
\end{align*}
$$

where $p_{n}$ has the meaning of the probability that all of the $n$ points belong to region $U_{2}$ occupied by the second component. Formulas (2.5) assume the form

$$
\begin{align*}
& P_{n}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n} v_{2}^{q} D_{n-q} \pi_{q}^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right)  \tag{3.2}\\
& T_{n}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}\left(-v_{2}\right)^{q} D_{n-q} \tau_{q}^{n}\left(\mathbf{R}_{q} ; \overline{\mathbf{R}}_{n-q}\right) \\
& D_{n}=v_{2}\left(1-v_{2}\right)^{n}+\left(1-v_{2}\right)\left(-v_{2}\right)^{n}
\end{align*}
$$

It follows from this that in the case of a two-dimensional medium the results correspond to the almost symmetric $N$-component medium. However the determination of central moments by (3.2) yields results that are substantially different from those derived by using (2.10),

In fact, using ( 2.6 ) we have

$$
\begin{equation*}
\dot{\mu_{n}^{(1)}}\left(\mathbf{R}_{n}\right)=T_{n}^{(1)}\left(\mathbf{R}_{n}\right)[\Delta \lambda \otimes]^{n}, \quad \Delta \lambda=\lambda_{2}-\lambda_{1} \tag{3.3}
\end{equation*}
$$

where, as before, the superscript indicates that the first component is taken as the separated one. The singularity of (3.3) is due to that in it the dependence on tensors is separated from the dependence on coordinates. The first of these is determined by tensor $[\Delta \lambda \otimes]^{n}$ and the second by function $T_{n}{ }^{(1)}\left(\mathbf{R}_{n}\right)$. Thus the form of central moments (3.3) with separated dependence on tensors and coordinates must be considered as specific to two-component media. A formula similar to (3.3) was obtained in the paper (*) in which a mixture of two isotropic components was considered.
*) Moskalenko, V. N. and Maslennikov, S. A., Properties of correlation functions of characteristics of micro-inhomogeneous material. Collection: Problems of Rellability in Structural Mechanics. Theses of proceedings of the All-Union Conference, Vil'mius, 1971.

Let us consider the symmetric medium in more detail. The transition from (1.1) to ( 2.11 ) in the case of a two-component medium is effected by the substitution

$$
\begin{equation*}
f_{1}^{(2)}(\mathbf{r})=1-f_{2}(\mathbf{r}), \quad f_{1}^{(1)^{\prime \prime}}(\mathbf{r})=-f_{2}^{\prime \prime}(\mathbf{r}) \tag{3.4}
\end{equation*}
$$

which makes it possible to express functions $P_{n}{ }^{(2)}$ and $T_{n}{ }^{(2)}$ determined with the use of $f_{1}^{(2)}$, in terms of $P_{q}^{(1)}$ and $T_{n}{ }^{(1)}$, respectively, as follows:

$$
\begin{equation*}
P_{n}^{(2)}\left(\mathbf{R}_{n}\right)=\sum_{\sigma_{n}} \sum_{q=0}^{n}(-1)^{q} P_{q}^{(1)}\left(\mathbf{R}_{n}\right), \quad T_{n}^{(2)}\left(\mathbf{R}_{n}\right)=(-1)^{n} T_{n}^{(1)} \tag{3.5}
\end{equation*}
$$

Functions $P_{q}^{(1)}$ and $T_{n}{ }^{(1)}$ appearing in the right-hand sides of (3.5) are deter mined according to (3.2), in terms of the second component concentration $v_{2}$ and of functions $\pi_{q}{ }^{n}$ and $\tau_{q}{ }^{n}$ whose properties are determined by the random field $f_{2}(r)$. Functions $P_{n}{ }^{(2)}$ and $T_{n}{ }^{(2)}$ can be expressed in the form (3.2). Then in the case of a symmetric medium functions $\pi_{q}{ }^{n}$ and $\tau_{q}{ }^{n}$ remain unchanged in virtue of (2.9), i. e, differences in component properties depend only on their concentration, while functions $P_{n}{ }^{(2)}$ and $T_{n}{ }^{(2)}$ are determined by formulas (3.2) in which $v_{1}=1-v_{2}$ must be substituted for $v_{2}$. We denote by $\bar{P}_{n}{ }^{(1)}$ and $\bar{T}_{n}{ }^{(1)}$ functions $P_{n}{ }^{(1)}$ and $T_{n}{ }^{(1)}$ in which inversion $2 \leftrightarrow 1$ has been effected. We then have

$$
\begin{equation*}
P_{n}^{(2)}=\bar{P}_{n}^{(1)}, \quad T_{n}^{(2)}=\bar{T}_{n}^{(1)} \tag{3.6}
\end{equation*}
$$

which with (3.5) yields

$$
\begin{equation*}
\bar{P}_{n}^{(1)}=\sum_{\sigma_{n}} \sum_{q=0}^{n}(-1)^{q} P_{q}^{(1)}, \quad \bar{T}_{n}^{(1)}=(-1)^{n} T_{n}^{(1)} \tag{3.7}
\end{equation*}
$$

Formulas (3.7) obtained as the corollary of the symmetry condition make it pos sible to simplify functions $P_{n}$ and $T_{n}$, which eventually results in functions $T_{n}$ being of the form (2.14).

Using (3.7) we shall show that $\tau_{2}{ }^{2}=0$. When $n=2$ we have for function $T_{n}$

$$
\begin{equation*}
\bar{T}_{2}^{(1)}=D_{2} \tau_{0}^{2}+v_{1}^{2} \tau_{2}^{2}=D_{2} \tau_{0}^{2}+v_{2}^{2} \tau_{2}^{2}=T_{2}^{(1)} \tag{3.8}
\end{equation*}
$$

from which, owing to $v_{1} \neq v_{2}$, we obtain the sought result.
It will be seen from ( 3.8 ) that the difference between symmetric and arbitrary inhomogeneous media become apparent already in the calculation of functions $T_{2}$. Properties of the first case medium are invariant with respect to component inversion $1 \leftrightarrow 2$, hence $\tau_{2}{ }^{2}=0$, while in the second $\tau_{\Omega}{ }^{2} \neq 0$. Let the second medium be a matrix one. Denoting function $T_{2}$ in the first and second cases by $T_{2}{ }^{s}$ and $T_{2}{ }^{m}$, respectively, we write

$$
T_{2}^{m}\left(\mathbf{R}_{2}\right)-T_{2}{ }^{s}\left(\mathbf{R}_{2}\right)=v_{2}^{2} \tau_{2}{ }^{2}\left(\mathbf{R}_{2}\right)
$$

Since according to (1.11) and (2.4) function $\tau_{2}{ }^{2}$ vanishes when $\mathbf{r}_{1}=\mathbf{r}_{2}$ and $\mid \mathbf{r}_{1}-$ $\mathbf{r}_{2} \mid \rightarrow \infty$, the observed discrepancy can only appear in the intermediate region. For Markovian type media [5] function $\tau_{2}{ }^{2}$ is everywhere zero.

A two-component medium considered in [2] satisfied the property

$$
\begin{equation*}
P_{n}{ }^{(2)}=P_{n}{ }^{(1)}, \quad T_{n}{ }^{(2)}=T_{n}{ }^{(1)} \tag{3.9}
\end{equation*}
$$

and was called symmetric. It will be seen that the concentrations of both components is then equal $1 / 2$. Furthermore, in virtue of (3.5) and (3.9) functions $P_{2 m+1}$ reduce to linear combinations of functions $P_{n}$ where $n \leqslant 2 m$, and $T_{2 m+1}$ vanish. Conditions (3.9) are the limit case of (3.6), since for $v_{1}=v_{2}=1 / 2$ and fulfilment of the sym metry conditions ( 3.6 ) converts to ( 3.9 ).

The requirement for identity of statistical properties of components of medium (3.9) substantially limits the class of media considered here. Conditions (3.6), on the other hand, represent the extension of the symmetry concept introduced in [2] to a wider class of two-component media, and conditions (2.9) extend it further to media with an arbitrary number of components.

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